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(74) Agents: WARDLE, Callum, Tarn et al.; Withers &
Rogers, Goldings House, 2 Hays Lane, London SE1 2HW
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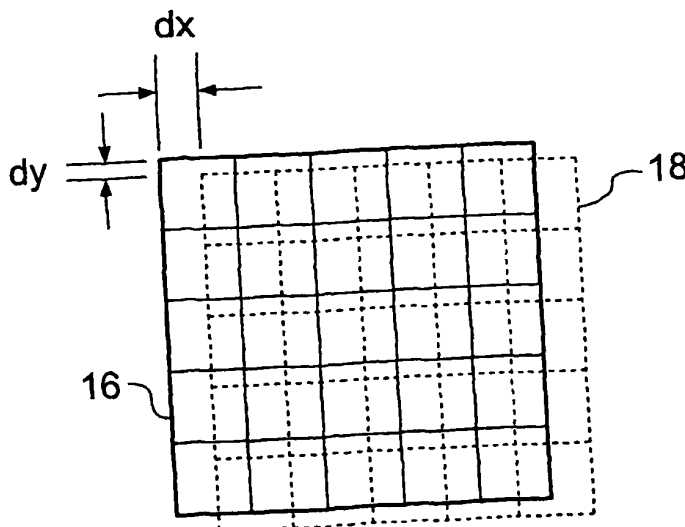
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UNIVERSITY OF BRISTOL [GB/GB]; Senate House,
Tyndall Avenue, Bristol BS8 1TH (GB).

(72) Inventors; and

(75) Inventors/Applicants (for US only): POTTER, Kevin,
David [GB/GB]; Easedale House, Church Lane, Backwell,
North Somerset BS48 3JJ (GB). SETCHELL, Christo-
pher [GB/GB]; c/o The University of Bristol, Senate
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(54) Title: POSITIONAL MEASUREMENT OF A FEATURE WITHIN AN IMAGE



(57) Abstract: The position of a feature within an image is determined by determining an initial estimate of the feature position to within a fraction of a pixel, translating the feature by an amount equal to that fraction of a pixel, determining a further estimate of the translated feature position to within a fraction of a pixel and summing the pixel fraction of the previous estimate with the further estimate of the position to arrive at a refined estimate of the feature position.

WO 2004/038328 A2